

Exercises April 16th 2004, Optimal Control of Economic Systems

1. Consider:

$$\begin{aligned}\dot{x}_1(t) &= -x_1(t)x_2(t) - x_1(t)x_2^2(t) \\ \dot{x}_2(t) &= x_1^2(t) - x_1^2(t)x_2(t) - x_2(t).\end{aligned}$$

- Determine all equilibrium points.
- Prove that the origin is stable.
- Is the origin asymptotically stable?

2. Investigate the stability of the origin for the following systems. Use a suitable Lyapunov function.

a.

$$\begin{aligned}\dot{x}_1(t) &= x_2(t) \\ \dot{x}_2(t) &= -x_1^3(t).\end{aligned}$$

b.

$$\begin{aligned}\dot{x}_1(t) &= -x_1^3(t) - x_2^2(t) \\ \dot{x}_2(t) &= x_1(t)x_2(t) - x_2^3(t).\end{aligned}$$

3. Consider the scalar equation

$$\dot{x}(t) = ax^3(t)$$

with $a \in \mathbb{R}$.

- Prove that the linearization of this system about its equilibrium point is independent of a .
- Prove that, depending on a , the equilibrium point may be asymptotically stable, stable but not asymptotically stable, and unstable.

4. Consider the system

$$\begin{aligned}\dot{x}_1(t) &= -2x_1(t) [x_1(t) - 1] [2x_1(t) - 1] \\ \dot{x}_2(t) &= -2x_2(t).\end{aligned}\tag{1}$$

- Calculate all equilibrium points of the system (1).
- Prove that there are two asymptotically stable equilibrium points.
- Investigate the stability of the other equilibrium point(s).