## Exercises werkcollege 6, FMSE

## Exercise 1

Consider the following FSP definitions:

```
BUFFER = (in -> out -> BUFFER).
| | SYNC_IN = (a:BUFFER || b:BUFFER)/{in/{a.in,b.in}}.
|SYSTEM = (SYNC_IN/{sync.ac/a.out, sync.bod/b.out}
    ||SYNC_OUT/{sync.ac/c.in,sync.bd/d.in})
    @ {in,out }.
```

a) Give a structured graph of the labelled transition system of SYSTEM. Label the states with tuples $(i, j, k, l)$, where $i, j, k, l$ are the respective local states of the processes $a: B U F F E R, b: B U F F E R, c: B U F F E R$ and $d: B U F F E R$, who collectively determine the global state of SYSTEM (so you can't just copy the the LTSA output).
b) Give a minimal automaton that is observation equivalent to SYSTEM. Give a sequential FSP process (i.e. without parallel composition or hiding) that is observation equivalent to SYSTEM.

## Exercise 2

Complete the MAZE example given in lecture 6 (slide 13). A path out of the maze is called balanced if and only if the number of north/south steps differs equals the number of east/west actions in the path. Modify your model such that for each initial square a shortest balanced path out of the maze, if it exists, is produced as a deadlock trace of the model. Determine the squares for which a balanced exit path exists.

## Exercise 3

One solution to the dining philosophers problem permits only 4 philosophers to sit down at the table at the same time. Specify a BUTLER process that, when composed with the model presented in lecture 6 (slide 9), permits a maximum of 4 philosophers to be seated concurrently at the table. Show that this system is deadlock-free.

## Exercise 4

What action trace violates the following safety property?

$$
\text { property } P S=(a->(b->P S \mid a->P S) \mid b->a->P S)
$$

## Exercise 5

A lift has a maximum capacity of ten people. In the model of the lift control system, passengers entering a lift are signalled by an enter action and passengers leaving the lift are signalled by and exit action. Specify a safety property in FSP that when composed with the lift will check that the system never allows the lift to have more than 10 occupants.

